

# ROTACOD

Absolute encoder with incremental serial interface

series

**Ax58 ISI**



AS58 ISI



[www.lika.biz](http://www.lika.biz)  
- application info  
- datasheet

## ENVIRONMENTAL SPECIFICATIONS

Shock:	100 g, 6 ms (acc. to MIL STD 202F)
Vibrations:	10 g, 5-2000 Hz (acc. to MIL STD 202F)
Operating temperature range:	-20°C +70°C (-4°F +158°F)
Storage temperature range:	-20°C +80°C (-4°F +176°F) (98% R.H.without condensation)
Protection:	IP65

## MECHANICAL SPECIFICATIONS

Dimensions:	see drawing
Shaft:	Ø 6, 8, 9.52, 10, 12 mm
Shaft loading (axial and radial):	40 N max.
Shaft rotational speed:	6000 rpm max.
Starting torque at 20°C:	< 1 Ncm (typical)
Moment of inertia:	~95 gcm <sup>2</sup>
Bearing life:	400x10 <sup>6</sup> rev. min. (10 <sup>9</sup> rev. min. with shaft loading of 20 N max.)
Peso/Weight:	~0,3 kg (10,6 oz)
Electrical connections:	EML 121 CONNE1 connector

## ELECTRICAL SPECIFICATIONS

STD pulse rate (other PPR upon request):	720 - 1024 - 2048
Power supply:	+10V +30V
Input current:	250 mA max.
Output current (per channel):	40 mA max.
Output frequency:	50 kHz max.
Protection:	against inversion of polarity
Optoelectronic life:	100.000 h min.

## MATERIALS

Housing:	non corroding
Flange:	non corroding
Bearings:	ABEC 5
Shaft:	stainless steel, non-magnetic
Light source:	GaAl diodes

## ELECTRICAL CONNECTIONS

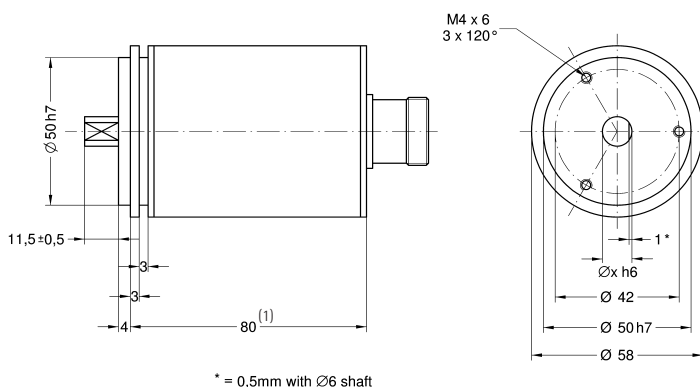
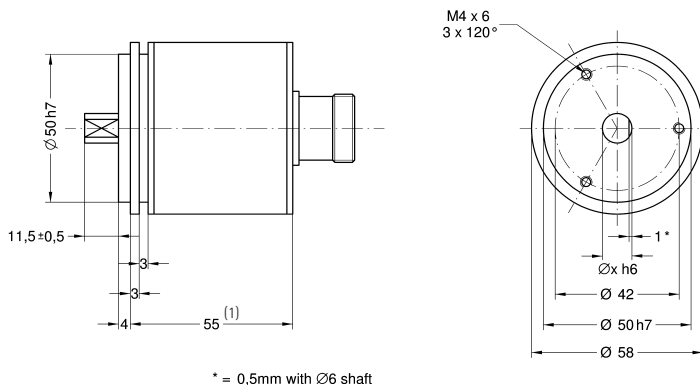
12 pin IP65 mating connector			
1	A	7	n.c.
2	/A	8	Error output
3	B	9	Zero setting
4	/B	10	Complementary
5	0	11	+10Vdc +30Vdc
6	/0	12	0 Vdc

## ACCESSORIES

EPFL 121:	12 pin CONNE1 mating connector
PAN/PGF:	flexible couplings
LKM-386:	finxing clamps

Specifications subject to changes without prior notice

**PH SYSTEMS - [www.phsystems.be](http://www.phsystems.be) - [sales@phsystems.be](mailto:sales@phsystems.be)**



(1) Mechanical dimensions with connector output see on page 64

**ISI - Incremental serial interface**

The absolute encoder with ISI interface, supplies an incremental output with A and channel (90° shifted) and index pulse. When switched on and enabled the encoder gives out a pulse train corresponding to the current absolute position. This allows to measure absolute positions even if the following electronics has only an incremental encoder input. Encoders with ISI interface are available as single turn and multi turn.

<p style="text-align: center;"><b>ORDERING CODE</b></p> <p style="text-align: center;">XXXX / XX - X X - X - X</p> <p style="text-align: center;">SERIES</p> <p style="text-align: center;">AS58</p> <p style="text-align: center;">PULSE RATE (PPR)</p> <p style="text-align: center;">80 = 720 PPR 12 = 1024 PPR 13 = 2048 PPR</p> <p style="text-align: center;">OUTPUT CODE</p> <p style="text-align: center;">ISI incremental serial interface S</p> <p style="text-align: center;">OUTPUT CIRCUITS</p> <p style="text-align: center;">Push-Pull Y Line Driver L</p>	<p style="text-align: center;"><b>ADDITIONAL CODE</b> (indicate only if necessary)</p> <p style="text-align: center;">R Side mount connector</p> <p style="text-align: center;">SHAFT Ø</p> <p style="text-align: center;">6 6 mm 8 8 mm 9.52 9.52 mm/ 3/8" 10 10 mm 12 12 mm</p>
<p style="text-align: center;"><b>ORDERING CODE</b></p> <p style="text-align: center;">XXXX X X X - X - X</p> <p style="text-align: center;">SERIES</p> <p style="text-align: center;">AM58</p> <p style="text-align: center;">PULSE RATE</p> <p style="text-align: center;">12/4096 = 1024 PPR x 4096 rev. 13/4096 = 2048 PPR x 4096 rev.</p> <p style="text-align: center;">OUTPUT CODE</p> <p style="text-align: center;">ISI incremental serial interface S</p>	<p style="text-align: center;"><b>ADDITIONAL CODE</b> (indicate only if necessary)</p> <p style="text-align: center;">R Side mount connector</p> <p style="text-align: center;">SHAFT Ø</p> <p style="text-align: center;">6 6 mm 8 8 mm 9.52 9.52 mm/ 3/8" 10 10 mm 12 12 mm</p> <p style="text-align: center;">OUTPUT CIRCUITS</p> <p style="text-align: center;">Y Push-Pull L Line Driver</p>